

# M-10iD/10L



Max. load capacity  
at wrist: 10 kg



Max. reach:  
1636 mm

# FANUC

| Robot  |         |      | Max. load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range (°) |     |     |     |     |     | Maximum speed (°/s) |     |     |     |     |     | J4 Moment/ Inertia | J5 Moment/ Inertia | J6 Moment/ Inertia | Average Power consumption (kW) | Protection             |                                  |
|--------|---------|------|----------------------------------|------------|-----------------|--------------------|------------------------|------------------|-----|-----|-----|-----|-----|---------------------|-----|-----|-----|-----|-----|--------------------|--------------------|--------------------|--------------------------------|------------------------|----------------------------------|
| Series | Version | Type |                                  |            |                 |                    |                        | J1               | J2  | J3  | J4  | J5  | J6  | J1                  | J2  | J3  | J4  | J5  | J6  |                    |                    |                    |                                | Body standard/optional | Wrist & J3 arm standard/optional |
| M-10   | iD      | 10L  | 10                               | 1636       | 6               | ±0.03**            | 150                    | 340 (370)        | 235 | 455 | 380 | 360 | 900 | 260                 | 240 | 260 | 430 | 450 | 720 | 22/.65             | 22/.65             | 9.8/.17            | 1                              | IP54/<br>IP55          | IP67                             |

● standard ○ on request - not available \*\* Based on ISO9283 \*\*\*with food grease

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Long arm, hollow wrist



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